Overview of Virtualization Techniques

There are many different virtualization techniques available across the operating systems in use today. The most basic virtualization is the concept of a software process. This is the traditional virtualization that Unix and many other operating systems have provided to different processes from early on: each user process has an independent, protected-access memory map provided through the virtual memory system of the kernel. Other more comprehensive virtualization techniques, such as software, hypervisor-based, hypervisor-based with hardware acceleration and containerized applications, will be reviewed.

Software Virtualization/Emulation

Software-based, complete machine emulators, such as QEMU and SIMH, can emulate practically any CPU and machine architecture on the hosting machine. These types of emulators are generally fairly slow, but offer complete independence between the emulated hardware and the
hosting machine. The emulation software provides an instruction by instruction emulation of the target machine and provides a software implementation of the hardware devices of the target machine. For example, disk drives on the target are often emulated with plain files on the hosting machine. Even machines that no longer have operating hardware, such as the Honeywell DPS8M, can be emulated. In this case, the emulation is of sufficient fidelity to allow the historically significant Multics operating system to run on the emulated machine with no software changes. Another significant example of this type of emulator was the Connectix Virtual PC software, which could emulate a complete x86 computer, hosted on a PowerPC-based Mac computer. The Connectix company was purchased by Microsoft and the software is no longer available.

Hypervisor-Based Virtualization

At the opposite end of the virtualization spectrum are hypervisor-based implementations. A hypervisor-based virtualization generally runs at a significant percentage of the native speed of the hosting machine. Only a small set of hypervisor-mediated system functions execute in the hypervisor and the rest of the user code runs in the virtualized machine at native speeds. This type of virtualization is considered fairly "heavyweight," in that each virtualized machine has its own copy of whatever operating system is being run. One area of performance issues with this scheme is that the virtualized operating system also has to maintain its own set of memory protections for its own use. Hardware support for this type of operation, sometimes called "nested page tables," greatly enhances the operation of guest operating systems under the hypervisor.

There are many hypervisor-based virtualization platforms available, including:

- bhyve on FreeBSD
- KVM on Linux
- xhyve on MacOS X
- Hyper-V on Microsoft Windows
- ESXi and vSphere from VMware
- Xen on multiple operating systems and several hardware architectures

Containerized Virtualization

Containers are lightweight virtualization schemes where processes have some sort of partitioning and isolation between different administrative groups on the same host. The different partitions all share a single kernel application binary interface (ABI), running against a single kernel instance. Often, but not always, each process running in a container can be seen on the hosting server. This type of virtualization is generally called "container computing," and offers a middle ground between the level of isolation from hypervisors and the "shared everything" from a standard Unix environment.

Containerization is the fundamental idea behind the following facilities:
- Jail system on FreeBSD
- Control Groups on Linux
- Containers on Nexenta OS
- Containers on Solaris

Hybrid Virtualization Techniques

There are other hybrid virtualization techniques, such as running a combination of hypervisor virtual machines and then hosting various containerized applications on those virtual machines. This hybrid approach is how Docker is implemented on non-Linux machines such as the MacOS xhyve virtualized machine. In a similar fashion, the Windows implementation of Docker uses the Hyper-V hypervisor to create a virtual machine running Linux, which is then used to execute the system calls from the Docker containers.

Linux Control Groups and Docker

The Linux kernel has a relatively new capability that makes Docker possible: Control Groups (aka "cgroups"). This is the fundamental technology that allows for the isolation of various user processes in one control group from affecting and directly interacting with a different control group.

In a traditional Unix environment, there is a single hierarchy of user processes. The init process (pid 1) is the root of that hierarchy, and all processes can trace their ancestry back to that initial process. The cgroups facility in the Linux kernel allows for instantiating new hierarchies of processes that are contained entirely in the new hierarchy, and can only interact with other processes in that hierarchy.
The cgroups facility can do more than just create new process hierarchies; it can set up resource limits (for example, memory and network bandwidth) and attach these limits to the process hierarchies that are created. While management of the low-level cgroups mechanism via provided system utilities is possible, it is rather tedious. Docker provides a more convenient interface for controlling the cgroups mechanism at runtime, along with an easy-to-use system for building the static environments that will be executed later.

Docker uses cgroups, along with other Linux kernel facilities, such as iptables, for networking configuration and control and for a union filesystem (UnionFS) for isolating the container from the filesystems of the hosting machine. There is also a mechanism available to allow explicit sharing of directories between the host machine and the Docker containers. The union filesystem that Docker implements is layered on top of a Docker storage driver. The storage drivers that are available depend on the particular Linux system that is running Docker and provide varying degrees of performance and stability.

### Docker Terminology and Software Architecture

An image is what Docker calls the containerized filesystem that has been created and loaded with the software layers that are needed for a particular application. When an image needs to run, a copy-on-write snapshot of the image is created, and that copy-on-write filesystem is called the container.

The process that starts a container is then placed into a new cgroup hierarchy. Any new processes spawned by the initial process in a Docker container will not be able to influence any processes outside of the running container, because all other processes will belong to different cgroups. This
isolation prevents any interaction or interference between two or more Docker containers running on the same physical host.

A modern Docker installation typically has at least two long-running daemons, *dockerd*, and *docker-containeerd*. There is a single user command, *docker*, that takes multiple command keywords. This is similar to how many complex systems are controlled through a single dispatch command (for example, *git*, *hg*, and *rndc*). The docker command communicates through a Unix domain socket to the *dockerd* process. The *dockerd* process communicates with the *dock-er-containeerd* process to specify the management of the containers on a system. There are other container software shims that are started for each container. The *runC* container runtime initializes and starts the container, and then hands the file descriptors for *stdin/stdout/stderr* over to *containerd-shim*, which acts as a proxy of sorts between the running *container* and *docker-containeerd*. This intermediate process is required so that a restart of the *dockerd* process, and therefore, the restart of *docker-containeerd* daemon to reattach to the *containerd-shim* for each currently running container.

### Docker Images Explained

A Docker image is a virtual filesystem, packaged as a series of layers. Each layer in the filesystem is stacked on top of the layers underneath it. The ultimate view of the filesystem is the union of the filesystems that make up a Docker image. The layers in the image are built from the commands in a Dockerfile.

### Dockerfile as a Recipe

The Dockerfile is a simple text file, holding one or more commands, and any comments that the user has placed in the file. When Docker builds an image, it runs each of the commands found in the file, in the order they are encountered. In this manner, the docker build procedure is just like following a step-by-step recipe for preparing a meal. Each of the commands in the Dockerfile will generate a new layer in the resulting image. By convention, the Docker commands are written in uppercase to help differentiate them from user-specified commands. If any of the commands that are executed fail (that is, has a non-zero exit code), the building of the image stops immediately and the image build is marked as a failure. For efficiency reasons, it is desirable to keep each layer in the Dockerfile as small as possible. This means that cleaning up after any commands that create large amounts of metadata, such as ‘*yum update*’, should be done as part of the same command that generated the metadata.

The example Dockerfile will create an image with six layers. Some of those layers, which are identical to the prior layer, will be automatically discarded during the build process. Example: Dockerfile for running Apache

```bash
# An image for running Apache
FROM centos:7
MAINTAINER Ms. Nobody <nobody@example.com>
RUN yum -y --setopt=tsflags=nodocs update && 
    yum -y --setopt=tsflags=nodocs install httpd && 
    yum clean all
VOLUME ["/var/www/html", "/var/log/httpd"]
EXPOSE 80
CMD ["/usr/sbin/apachectl", "/DFOREGROUND"]
```

The first command, ‘*FROM centos:7*’, which creates the first layer in the image, specifies that that base image for *CentOS 7* should be pulled from the central Docker repository into the local machine’s cache of filesystem layers. This layer is
the bottom layer in the image. The 'FROM' command must be the first command in a Dockerfile and initializes a new build.

The second command, 'MAINTAINER ...', sets a special label in the metadata for the image. This label is used to identify the creator of the image. There is also a 'LABEL' command that could be used instead, to set an arbitrary number of labels on an image. The labels can be used by the end user for any purpose.

The third command, 'RUN yum -y update ...' updates any out-of-date software packages that were included in the base image. The next command, 'yum -y install httpd', installs the Apache 'httpd' package. The final part of the command, 'yum clean', expunges all the package/repository metadata maintained by the yum package management system, to minimize the size of the generated layer. For the same reason, the yum command, using the nodocs flag, is instructed to ignore any documentation during the upgrade and installation of packages. The arguments to the 'RUN' command are executed by a shell process, so the complexity of the generated layer in the constructed image can be quite elaborate.

The fourth command, 'VOLUME [ ... ]', marks a list of directories to be used as external mountpoints in the UnionFS filesystem. During container execution, these mountpoints will have external filesystems mounted at these locations. The UnionFS layer should not attempt to capture that activity to the copy-on-write filesystem. This is one method how a container can persist data outside of the copy-on-write image from which the container is executing.

The fifth command, 'EXPOSE 80', provides information that will be used when a container is started from this image. A port on the hosting machine can be mapped to the specified TCP port number of the container at runtime. Or, by specifying a different network-
mand. Not all the metadata is shown in this output (above), just some of the more interesting pieces.

The "ContainerConfig" section has the complete environment specified for the processes in any containers that are started from this image. The "Architecture" and "Os" settings show that the containers support the Linux syscall interface, for the amd64 (aka "x86_64") machine type. The Docker image for this article was created on a Macintosh computer, running macOS Sierra 10.12.5, but any containers will be executed with a Linux/amd64 runtime environment.

This image could be moved to any host capable of running Linux/amd64 Docker images. The portability of images is one of the principle advantages of Docker ease-of-building and deploying across many different hosts, without having to worry about shared library conflicts, or corrupting configurations of already installed components. Docker supports image registries where images may be stored and retrieved. A private Docker registry can be created that allows users to centrally store their customized images. Once the image is stored in the registry, a single command can retrieve the image to a host, and a second command can start a container from that image.
Running a Container

It is easy to create a running container from the example image:

```
# docker run --rm -d -p 8080:80 \
-v $(pwd)/htdocs:/var/www/html \
-v $(pwd)/logs:/var/log/httpd \
centos-apache-testimage:latest
```

This command starts the container, telling Docker to throw away the copy-on-write filesystem (--rm) when the container exits. Run the container in the background (-d) and port-map localhost:8080 to the container's tcp port 80 (-p 8080:80). Perform volume mounts of $(pwd)/htdocs to the DocumentRoot of the webserver (-v $(pwd)/htdocs:/var/www/html), and mount $(pwd)/logs to hold the log files from the web server running in the container (-v $(pwd)/logs:/var/log/httpd). Finally, the name of the image to be used as the initial filesystem for the container is given.

Looking at Running Containers

Once a container has been started, it will run until the initial process that started the container exits. The user that started the container, or system administrator, can stop the container via the docker stop command. This sends a SIGTERM to the initial process in the container, and then a SIGKILL after a grace period, if the container has not stopped. This is very similar in intent to running the shutdown command on a Unix host. The docker kill command just sends a SIGKILL to the root process in the container.

The docker ps command gives the list of running containers. The docker rm command can be used to remove the copy-on-write filesystem of a stopped container.

Looking at Images on the Machine

The docker images command will show the list of images currently available on the host.

The docker rmi command can be used to remove a reference to an image, freeing the storage associated with that image when the reference count drops to zero. Note that shared layers in the image may also be used by other images, so there often isn’t a one-to-one correspondence between the amount of space listed as in use for the image and the amount of disk space used by the image. Many of the issues with double-counting of storage blocks that occur with filesystem snapshots are also evident with the docker- containerd storage of images.

Other Docker Commands

There are other Docker commands available that can be used for launching containers automatically and maintaining a set of containers that must run together to accomplish a given task. It is beyond the scope of this article to fully examine the complete set of commands available inside of Docker. More advanced orchestration of multiple containers running across multiple hosts is possible via the "Docker Swarm" support in recent versions of Docker.

Comparison with FreeBSD Jails

Docker containers are similar to FreeBSD jails, in terms of what virtualization is provided and how machine resources are shared. Both offer compartmentalized processes running against a single kernel image on the hosting machine. Docker offers an easy-to-use command line interface for creating, deploying, running, and updating images. Little setup and configuration are required on the hosting machine, other than the basic Docker Engine installation. FreeBSD jails have a considerably simpler interface to running and stopping jails. The base FreeBSD system offers essentially no high level support for the building and installation of jails into a directory. There are several add-on FreeBSD ports (for example, ezjail, qjail, and qjail4) that attempt to make jail usage less cumbersome, to varying degrees of success.

One significant advantage that Docker has over jails is the concept of spawning a per-instance copy-on-write filesystem for each container that is started. This is fundamental to the deployment and reusability of Docker images, whereas each FreeBSD jail typically runs in a persistent filesystem tree. Some of the add-on jail management systems use ZFS’s snapshot and promote features to create a clone of a prototype filesystem for a newly instantiated jail, but that clone still persists the file hierarchy across multiple restarts of the jail.
With Docker containers, the Docker infrastructure takes care of mounting various directories when the container is started, whereas mounting of any directories, even including the crucial `devfs /dev mount`, must be handled explicitly for each FreeBSD jail.

For example, running the example docker container for apache, there are several mount-points active:

```bash
# df
Filesystem  1K-blocks  Used  Available  Use%  Mounted on
none        61890340  863500  57859916  2%    /
tmpfs       1023384   0    1023384  0%    /dev
/dev/sda2   61890340  863500  57859916  2%    /sys/fs/cgroup
shm         65536    0    65536    0%    /dev/shm
osxfs       976426656 624064128 352106528 64%   /var/www/html
tmpfs       1023384   0    1023384  0%    /sys/firmware
```

The Docker system manufactured the required mounts automatically, with the exception of the `/var/www/html` mount, which was specified on the command line when the container was started.

The security benefits of Docker vs jails are roughly equivalent. The security features of Docker are typically modified through command-line flags, while the security features for jails are either globally specified via sysctl settings, or have per-jail configuration settings in the `/etc/jail.conf` file. Jails, when operated with the VIMAGE networking option, have a per-instance network stack. This implies that each jail could have different packet filtering in place. All the running containers on a Linux-based host share a single iptables-based packet filter configuration.

The control aspects of Docker vs jails are quite different. Docker has many commands and options to allow almost all configurations to happen on the command line. FreeBSD jails rely heavily on the contents of the `/etc/jail.conf` file to specify which jails are to be run and how they are to be configured. Docker internalizes much of the configuration that is the metadata for a given Docker image. By attaching this metadata to the image, the deployment to a new host is significantly eased. FreeBSD jails have no such metadata directly attached to each jail.

In a related area, some of the FreeBSD ports for helping to manage bhyve virtualized host instances, such as `iohyve`, offer some of the same type of configuration help. These systems use ZFS properties to attach the metadata about a virtualized machine to a ZFS filesystem or ZFS zvol, which represents the filesystem for the virtualized machine. Several of the earliest versions of these management tools just used well-known names for the parameters that were to be controlled: hostname, number of cpus, amount of memory, and so forth. None offered a generic, extensible `tag:value` configuration file that could be attached to a ZFS filesystem, although this might have changed since the earliest attempts at supporting virtual machine metadata in this manner.

**Future Directions for Docker**

The Docker system is undergoing fairly rapid evolution. There is a consortium of companies that have formed the Open Container Initiative (OCI). Significant members of the OCI include Amazon, AT&T, Cisco, Docker Inc., Facebook, Google, IBM, Microsoft, Oracle, RedHat, and VMware. OCI is attempting to standardize both a container runtime system ("runtime-spec") and an image specification ("image-spec"). As a starting point for the standardization process, Docker Inc. donated their container specification to OCI, and their runtime system ("runc"). Some of the members of OCI have vested interests in supporting more than just a Linux syscall ABI container, and the specifications are clear in the need to support multiple ABIs, as well as multiple operating systems hosting the container runtime. A recent development in the standardization process is Oracle's release of an open-source implementation of the oci-runtime called Railcar, which is written in Rust.
Docker on FreeBSD?

Examining the current state of the Docker system, it seems that there are no insurmountable technical impediments to making the Docker system run natively on FreeBSD. The future of Docker and the support for different ABIs across containers implies that supporting a native FreeBSD kernel ABI for the containers would be possible. Obviously, this makes deployment using Docker less of a Linux/amd64 monoculture. Currently, Docker is effectively only running the Linux ABI on amd64 hardware. The Docker community, through the OCI, has already tentatively agreed to a multi-architecture system where both Linux and Windows will be supported as first-class ABI environments, across multiple hardware platforms. This cross-system support is already available in a limited fashion for the Linux ABI on IBM’s Z-System hardware, and nascent support for the arm64 architecture is available as well. It should be possible to extend this multi-ABI future to include FreeBSD.

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